Qian, Klasnja, and Murphy's Linear Mixed Effects Model with Endogenous Covariates

Hunyong Cho, Josh Zitovsky, Matthew Brown, Xinyi Li, Minxin Lu, Kushal Shah, John Sperger, and Michael Kosorok

University of North Carolina at Chapel Hill

1/24/2020



Linear mixed models with endogenous covariates: modeling sequential treatment effects with application to a mobile health study

Tianchen Qian, Predrag Klasnja and Susan A. Murphy

Department of Statistics, Harvard University, Cambridge, MA 02138 e-mail: qiantianchen@fas.harvard.edu; samurphy@fas.harvard.edu.

School of Information, University of Michigan, Ann Arbor, MI 48109 e-mail: klasnja@umich.edu.

Abstract: Mobile health is a rapidly developing field in which behavioral treatments are delivered to individuals via wearables or smartphones to facilitate health-related behavior change. Micro-randomized trials (MRT) are an experimental design for developing mobile health interventions. In an MRT the treatments are randomized numerous times for each individual over course of the trial. Along with assessing treatment effects, behavioral scientists aim to understand between-person heterogeneity in the treatment effect. A natural approach is the familiar linear mixed model. However, directly applying linear mixed models is problematic because potential moderators of the treatment effect are frequently endogenous—that is, may depend on prior treatment. We discuss model interpretation and biases that arise in the absence of additional assumptions when endogenous covariates are included in a linear mixed model. In particular, when there are endogenous covariates, the coefficients no longer have the customary marginal interpretation. However, these coefficients still have a conditional-onthe-random-effect interpretation. We provide an additional assumption that, if true, allows scientists to use standard software to fit linear mixed model with endogenous covariates, and person-specific predictions of effects can be provided. As an illustration, we assess the effect of activity suggestion in the HeartSteps MRT and analyze the between-person treatment effect heterogeneity.

- 1. Classic Linear Mixed Effects Models (LMM)
- 2. QKM's LMM for endogenous covariate data
- 3. Our discussion

1. Classic Linear Mixed Effects Models

•
$$Y_{i,t+1} = X_{i,t}\beta + Z_{i,t}b_i + \epsilon_{i,t+1},$$
 $i = 1, 2, ..., n; t = 1, 2, ..., T$
• $\epsilon_{i,t+1} \sim N(0, \sigma^2 I)$

• $b_i \sim N(0,G)$

•
$$Y_{i,t+1} = X_{i,t}\beta + Z_{i,t}b_i + \epsilon_{i,t+1}$$
,

•
$$\epsilon_{i,t+1} \sim N(0,\sigma^2 I)$$

• $b_i \sim N(0,G)$

One more important assumption:

$$i = 1, 2, ..., n; t = 1, 2, ..., T$$

•
$$Y_{i,t+1} = X_{i,t}\beta + Z_{i,t}b_i + \epsilon_{i,t+1}$$
,

•
$$\epsilon_{i,t+1} \sim N(0,\sigma^2 I)$$

• $b_i \sim N(0,G)$

One more important assumption:

•
$$X_{i,t}$$
 is {fixed},

$$i = 1, 2, ..., n; t = 1, 2, ..., T$$

•
$$Y_{i,t+1} = X_{i,t}\beta + Z_{i,t}b_i + \epsilon_{i,t+1}$$

- $\epsilon_{i,t+1} \sim N(0,\sigma^2 I)$
- $b_i \sim N(0,G)$

One more important assumption:

- $X_{i,t}$ is {fixed},
- or $\{exogenous \& independent of b_i\}$.

$$i = 1, 2, ..., n; t = 1, 2, ..., T$$

•
$$Y_{i,t+1} = X_{i,t}\beta + Z_{i,t}b_i + \epsilon_{i,t+1},$$
 $i = 1, 2, ..., n; t = 1, 2, ..., T$

- $\epsilon_{i,t+1} \sim N(0,\sigma^2 I)$
- $b_i \sim N(0,G)$

One more important assumption:

- $X_{i,t}$ is {fixed},
- or {exogenous & independent of b_i }.

Thanks to the independence $(X_{i,t} \perp b_i)$, β has a marginal interpretation!

•
$$Y_{i,t+1} = X_{i,t}\beta + Z_{i,t}b_i + \epsilon_{i,t+1},$$
 $i = 1, 2, ..., n; t = 1, 2, ..., T$

- $\epsilon_{i,t+1} \sim N(0,\sigma^2 I)$
- $b_i \sim N(0,G)$

One more important assumption:

- *X_{i,t}* is {fixed},
- or $\{exogenous \& independent of b_i\}$.

Thanks to the independence $(X_{i,t} \perp b_i)$, β has a marginal interpretation!

• from
$$E[Y_{i,t}|X_{i,t}, b_i] = X_{i,t}\beta + Z_{i,t}b_i$$
, we get
 $E[Y_{i,t}|X_{i,t}] = X_{i,t}\beta + \underbrace{E[Z_{i,t}b_i]}_{=Z_{i,t}E[b_i|X_i]=Z_{i,t}E[b_i]=0} = X_{i,t}\beta.$

Consider a micro-randomized trial (MRT).

• We need treatment variable $(A_{i,t})$:

 $Y_{i,t+1} = X_{i,t}\beta_0 + A_{i,t}X_{i,t}\beta_1 + Z_{i,t}b_{0,i} + A_{i,t}Z_{i,t}b_{1,i} + \epsilon_{i,t+1}.$

Consider a micro-randomized trial (MRT).

• We need treatment variable $(A_{i,t})$:

 $Y_{i,t+1} = X_{i,t}\beta_0 + A_{i,t}X_{i,t}\beta_1 + Z_{i,t}b_{0,i} + A_{i,t}Z_{i,t}b_{1,i} + \epsilon_{i,t+1}.$

• Want to use historical information $(H_{i,t})$ for the next treatment, not only the current covariate $(X_{i,t})$.

$$H_{i,t} = (X_{i,1}, A_{i,1}, Y_{i,2}, \dots, X_{i,t-1}, A_{i,t-1}, Y_{i,t}, X_{i,t}).$$

Consider a micro-randomized trial (MRT).

• We need treatment variable $(A_{i,t})$:

 $Y_{i,t+1} = X_{i,t}\beta_0 + A_{i,t}X_{i,t}\beta_1 + Z_{i,t}b_{0,i} + A_{i,t}Z_{i,t}b_{1,i} + \epsilon_{i,t+1}.$

• Want to use historical information $(H_{i,t})$ for the next treatment, not only the current covariate $(X_{i,t})$.

$$H_{i,t} = (X_{i,1}, A_{i,1}, Y_{i,2}, \dots, X_{i,t-1}, A_{i,t-1}, Y_{i,t}, X_{i,t}).$$

• $Y_{i,t+1} = f_0(H_{i,t})^\top \beta_0 + A_{i,t} f_1(H_{i,t})^\top \beta_1 + g_0(H_{i,t})^\top b_{0,i} + A_{i,t} g_1(H_{i,t})^\top b_{1,i} + \epsilon_{i,t+1}.$ *f.* and *g.* are some summary functions with a fixed dimension.

Consider a micro-randomized trial (MRT).

• We need treatment variable $(A_{i,t})$:

 $Y_{i,t+1} = X_{i,t}\beta_0 + A_{i,t}X_{i,t}\beta_1 + Z_{i,t}b_{0,i} + A_{i,t}Z_{i,t}b_{1,i} + \epsilon_{i,t+1}.$

• Want to use historical information $(H_{i,t})$ for the next treatment, not only the current covariate $(X_{i,t})$.

$$H_{i,t} = (X_{i,1}, A_{i,1}, Y_{i,2}, \dots, X_{i,t-1}, A_{i,t-1}, Y_{i,t}, X_{i,t}).$$

- $Y_{i,t+1} = f_0(H_{i,t})^\top \beta_0 + A_{i,t} f_1(H_{i,t})^\top \beta_1 + g_0(H_{i,t})^\top b_{0,i} + A_{i,t} g_1(H_{i,t})^\top b_{1,i} + \epsilon_{i,t+1}.$
 - f. and g. are some summary functions with a fixed dimension.
- Is there any problem using LMM for this model?

Consider a micro-randomized trial (MRT).

• We need treatment variable $(A_{i,t})$:

 $Y_{i,t+1} = X_{i,t}\beta_0 + A_{i,t}X_{i,t}\beta_1 + Z_{i,t}b_{0,i} + A_{i,t}Z_{i,t}b_{1,i} + \epsilon_{i,t+1}.$

• Want to use historical information $(H_{i,t})$ for the next treatment, not only the current covariate $(X_{i,t})$.

$$H_{i,t} = (X_{i,1}, A_{i,1}, Y_{i,2}, \dots, X_{i,t-1}, A_{i,t-1}, Y_{i,t}, X_{i,t}).$$

• $Y_{i,t+1} = f_0(H_{i,t})^\top \beta_0 + A_{i,t} f_1(H_{i,t})^\top \beta_1 + g_0(H_{i,t})^\top b_{0,i} + A_{i,t} g_1(H_{i,t})^\top b_{1,i} + \epsilon_{i,t+1}.$

 f_{\cdot} and g_{\cdot} are some summary functions with a fixed dimension.

- Is there any problem using LMM for this model?
- No, $X_{i,t}$ is often endogenous.

What is a endogenous covariate?

Exogenous = X is not affected by any variables in the model (e.g. temperature, pre-scheduled / fixed variables, etc)

$$X_{i,t} \perp (H_{i,t-1}, A_{i,t-1}, Y_{i,t})$$

• Endogenous = X is affected by some variables in the model (e.g. past outcomes)

$$X_{i,t} = f(H_{i,t-1}, A_{i,t-1}, Y_{i,t})$$

for some function f.

2. QKM's LMM with endogenous covariates

- Want to increase the amount of patients exercise (Y) by push alarm intervention (A)
- We either have push alarm or not every two hours.
- $X_{i,t} =$ number of steps taken during 30 mins before treatment $(A_{i,t})$
- $Y_{i,t+1} =$ number of steps taken during 30 mins after $A_{i,t}$

•
$$(X_{i,1}, A_{i,1}, Y_{i,2}), \dots, (X_{i,t-1}, A_{i,t-1}, Y_{i,t}), (X_{i,t}, A_{i,t}, Y_{i,t+1}), \dots$$

=: $H_{i,t}$

- Want to increase the amount of patients exercise (Y) by push alarm intervention (A)
- We either have push alarm or not every two hours.
- $X_{i,t} =$ number of steps taken during 30 mins before treatment $(A_{i,t})$
- $Y_{i,t+1} =$ number of steps taken during 30 mins after $A_{i,t}$
- $\underbrace{(X_{i,1}, A_{i,1}, Y_{i,2}), \dots, (X_{i,t-1}, A_{i,t-1}, Y_{i,t}), (X_{i,t}, A_{i,t}, Y_{i,t+1}), \dots}_{=:H_{i,t}}$
- *X_{i,t}* is obviously endogenous!

The conditional independence assumption

$$X_{it} \perp (b_{0i}, b_{1i}) | H_{i,t-1}, A_{i,t-1}, Y_{i,t}$$
(10)

The conditional independence assumption

$$X_{it} \perp (b_{0i}, b_{1i}) | H_{i,t-1}, A_{i,t-1}, Y_{i,t}$$
(10)

 $\Rightarrow \text{ If this assumption (10) holds,} \\ \hat{\beta} \text{ estimated by standard LMM packages is a valid MLE.}$

QKM's LMM - quick proof

$$\begin{split} \prod_{i} p(X_{i}, A_{i}, Y_{i} | \alpha, \beta, \theta, \sigma_{\epsilon}) \\ &= \prod_{i} \int p(X_{i}, A_{i}, Y_{i} | b_{i}; \alpha, \beta, \theta, \sigma_{\epsilon}) dF(b_{i}) \\ &= \prod_{i} \{ \int \prod_{t} \underbrace{p(X_{i,t} | H_{i,t-1}, A_{i,t-1}, Y_{i,t}, b_{i})}_{=11A} \underbrace{p(A_{i,t} | H_{i,t}, b_{i})}_{=11B} \times \underbrace{p(Y_{i,t+1} | H_{i,t}, A_{i,t}, b_{i}; \alpha, \beta, \theta, \sigma_{\epsilon})}_{=11C} dF(b_{i}) \} \\ &= \{ \prod_{i} \prod_{t} p(X_{i,t} | H_{i,t-1}, A_{i,t-1}, Y_{i,t}) p(A_{i,t} | H_{i,t}) \} \times \underbrace{\prod_{i} \{ \int \prod_{t} p(Y_{i,t+1} | H_{i,t}, A_{i,t}, b_{i}; \alpha, \beta, \theta, \sigma_{\epsilon}) dF(b_{i}) \}}_{\mathcal{L}_{1}(\alpha, \beta, \theta, \sigma_{\epsilon} | X, A, Y)_{\mathcal{T}} \leftarrow \mathcal{T}_{2}(\mathbf{W}) \end{split}$$

$$\begin{split} \mathcal{L}(\alpha,\beta,\theta,\sigma_{\epsilon}|X,A,Y) = \\ \underbrace{\{\prod_{i}\prod_{t}p(X_{i,t}|H_{i,t-1},A_{i,t-1},Y_{i,t}) \ p(A_{i,t}|H_{i,t})\} \times}_{\text{Not involving } (\alpha,\beta,\theta,\sigma_{\epsilon})} \\ \underbrace{\prod_{i}\{\int\prod_{t}p(Y_{i,t+1}|H_{i,t},A_{i,t},b_{i};\alpha,\beta,\theta,\sigma_{\epsilon})dF(b_{i})\}}_{\mathcal{L}_{1}(\alpha,\beta,\theta,\sigma_{\epsilon}|X,A,Y) = \text{Likelihood of the classic LMM!}} \end{split}$$

~ ,/~ ,~ , .

$$\begin{split} \mathcal{L}(\alpha,\beta,\theta,\sigma_{\epsilon}|X,A,Y) = \\ \underbrace{\{\prod_{i}\prod_{t}p(X_{i,t}|H_{i,t-1},A_{i,t-1},Y_{i,t}) \ p(A_{i,t}|H_{i,t})\} \times}_{\text{Not involving } (\alpha,\beta,\theta,\sigma_{\epsilon})} \\ \underbrace{\prod_{i}\{\int\prod_{t}p(Y_{i,t+1}|H_{i,t},A_{i,t},b_{i};\alpha,\beta,\theta,\sigma_{\epsilon})dF(b_{i})\}}_{\mathcal{L}_{1}(\alpha,\beta,\theta,\sigma_{\epsilon}|X,A,Y) = \text{Likelihood of the classic LMM!}} \end{split}$$

$$\therefore \arg \max_{\xi} \mathcal{L}(\underbrace{\alpha, \beta, \theta, \sigma_{\epsilon}}_{=:\xi} | X, A, Y) = \arg \max_{\xi} \mathcal{L}_{1}(\alpha, \beta, \theta, \sigma_{\epsilon} | X, A, Y)$$

- Once conditional independence assumption holds,
- We can just use standard LMM package.
- Still, β only has conditional-on-random-effects interpretation.

3. Discussion

- Is partial likelihood okay to use?
- How to verify the conditional independence?
- Marginal effects estimation
- Nonlinear models kernel extension

QKM factored out the first two terms assuming that they do not involve $\xi \equiv (\alpha, \beta, \theta, \sigma_{\epsilon}).$

$$C(\alpha, \beta, \theta, \sigma_{\epsilon} | X, A, Y) = \underbrace{\{\prod_{i} \prod_{t} p(X_{i,t} | H_{i,t-1}, A_{i,t-1}, Y_{i,t}) \ p(A_{i,t} | H_{i,t})\}}_{\text{Not involving } (\alpha, \beta, \theta, \sigma_{\epsilon})} \prod_{i} \{\int \prod_{t} p(Y_{i,t+1} | H_{i,t}, A_{i,t}, b_{i}; \alpha, \beta, \theta, \sigma_{\epsilon}) dF(b_{i})\}}$$

 $\mathcal{L}_1(\alpha,\beta,\theta,\sigma_\epsilon|X,A,Y){=}\mathsf{Likelihood of the classic LMM!}$

Ĺ

QKM factored out the first two terms assuming that they do not involve $\xi \equiv (\alpha, \beta, \theta, \sigma_{\epsilon}).$

$$\begin{split} \mathcal{L}(\alpha,\beta,\theta,\sigma_{\epsilon}|X,A,Y) = \\ \underbrace{\{\prod_{i}\prod_{t}p(X_{i,t}|H_{i,t-1},A_{i,t-1},Y_{i,t}) \ p(A_{i,t}|H_{i,t})\} \times}_{\text{Not involving }(\alpha,\beta,\theta,\sigma_{\epsilon})} \\ \underbrace{\prod_{i}\{\int\prod_{t}p(Y_{i,t+1}|H_{i,t},A_{i,t},b_{i};\alpha,\beta,\theta,\sigma_{\epsilon})dF(b_{i})\}}_{t} \end{split}$$

 $\mathcal{L}_1(\alpha,\!\beta,\!\theta,\!\sigma_\epsilon|X,\!A,\!Y) {=} \mathsf{Likelihood of the classic LMM!}$

However, $X_{i,t}$ might have some information about ξ .

QKM factored out the first two terms assuming that they do not involve $\xi\equiv(\alpha,\beta,\theta,\sigma_\epsilon).$

$$\mathcal{L}(\alpha, \beta, \theta, \sigma_{\epsilon} | X, A, Y) = \underbrace{\{\prod_{i} \prod_{t} p(X_{i,t} | H_{i,t-1}, A_{i,t-1}, Y_{i,t}) \ p(A_{i,t} | H_{i,t})\} \times}_{\text{Not involving } (\alpha, \beta, \theta, \sigma_{\epsilon})} \underbrace{\prod_{i} \{\int \prod_{t} p(Y_{i,t+1} | H_{i,t}, A_{i,t}, b_{i}; \alpha, \beta, \theta, \sigma_{\epsilon}) dF(b_{i})\}}_{}$$

 $\mathcal{L}_1(\alpha,\!\beta,\!\theta,\!\sigma_\epsilon|X,\!A,\!Y) {=} \mathsf{Likelihood of the classic LMM!}$

QKM factored out the first two terms assuming that they do not involve $\xi \equiv (\alpha, \beta, \theta, \sigma_{\epsilon}).$

$$\mathcal{L}(\alpha, \beta, \theta, \sigma_{\epsilon} | X, A, Y) = \underbrace{\{\prod_{i} \prod_{t} p(X_{i,t} | H_{i,t-1}, A_{i,t-1}, Y_{i,t}) \ p(A_{i,t} | H_{i,t})\}}_{t} \times$$

Not involving $(\alpha, \beta, \theta, \sigma_{\epsilon})$

$$\prod_{i} \{ \int \prod_{t} p(Y_{i,t+1} | H_{i,t}, A_{i,t}, b_i; \alpha, \beta, \theta, \sigma_{\epsilon}) dF(b_i) \}$$

 $\mathcal{L}_1(\alpha,\!\beta,\!\theta,\!\sigma_\epsilon|X,\!A,\!Y) {=} \mathsf{Likelihood of the classic LMM!}$

However, $X_{i,t}$ might have some information about ξ . $\beta_1 : A_{i,t} \to Y_{i,t+1} \neg$ "treatment effect" $\delta_1 : A_{i,t} \to \to \to X_{i,t+1}$ "delayed treatment effect" β_1 and δ_1 may not be orthogonal. So omitting the two terms may cause efficiency loss!

$$X_{it} \perp (b_{0i}, b_{1i}) | H_{i,t-1}, A_{i,t-1}, Y_{i,t}$$
(10)

$$X_{it} \perp (b_{0i}, b_{1i}) | H_{i,t-1}, A_{i,t-1}, Y_{i,t}$$
(10)

• It is not testable without further assumption.

$$X_{it} \perp (b_{0i}, b_{1i}) | H_{i,t-1}, A_{i,t-1}, Y_{i,t}$$
(10)

- It is not testable without further assumption.
- QKM suggests using the domain knowledge to judge independence.

$$X_{it} \perp (b_{0i}, b_{1i}) | H_{i,t-1}, A_{i,t-1}, Y_{i,t}$$
(10)

- It is not testable without further assumption.
- QKM suggests using the domain knowledge to judge independence.
- When $H_{i,t-1}$ contains enough information, additionally having b_i may not help predicting X_{it} . Thus, it is likely conditionally independent.

$$X_{it} \perp (b_{0i}, b_{1i}) | H_{i,t-1}, A_{i,t-1}, Y_{i,t}$$
(10)

- It is not testable without further assumption.
- QKM suggests using the domain knowledge to judge independence.
- When $H_{i,t-1}$ contains enough information, additionally having b_i may not help predicting X_{it} . Thus, it is likely conditionally independent. $X_{i,t+1} = (f_1(\mathbf{H}_{i,t}), A_{i,t}, Y_{i,t+1})^T \gamma_1 + \eta_{i,t+1} \text{ v.s.}$ $X_{i,t+1} = (f_1(\mathbf{H}_{i,t}), A_{i,t}, Y_{i,t+1})^T \gamma_1 + b_i^T \gamma_2 + \eta_{i,t+1}$

Develop an ad-hoc test.

Develop an ad-hoc test.

Instead of testing

 $X_{it} \perp (b_{0i}, b_{1i}) | H_{i,t-1}, A_{i,t-1}, Y_{i,t} \quad \text{for all of } t = 1, 2, ..., T,$

Develop an ad-hoc test.

- Instead of testing $X_{it} \perp (b_{0i}, b_{1i}) | H_{i,t-1}, A_{i,t-1}, Y_{i,t} \text{ for all of } t = 1, 2, ..., T,$
- we test

 $X_{it} \perp (\hat{b}_{0i}, \hat{b}_{1i}) | s_d(H_{i,t-1}, A_{i,t-1}, Y_{i,t}) \quad \forall t \in \mathcal{T},$

where s_d is a d-dimensional summary function.

Develop an ad-hoc test.

- Instead of testing $X_{it} \perp (b_{0i}, b_{1i}) | H_{i,t-1}, A_{i,t-1}, Y_{i,t} \text{ for all of } t = 1, 2, ..., T,$
- we test

$$X_{it} \perp (\hat{b}_{0i}, \hat{b}_{1i}) | s_d(H_{i,t-1}, A_{i,t-1}, Y_{i,t}) \quad \forall t \in \mathcal{T},$$

where s_d is a *d*-dimensional summary function

• Conditional Distance Independence Test (CDIT) (Wang et al., 2015)

Develop an ad-hoc test.

- Instead of testing $X_{it} \perp (b_{0i}, b_{1i}) | H_{i,t-1}, A_{i,t-1}, Y_{i,t} \text{ for all of } t = 1, 2, ..., T,$
- we test

$$X_{it} \perp (\hat{b}_{0i}, \hat{b}_{1i}) | s_d(H_{i,t-1}, A_{i,t-1}, Y_{i,t}) \quad \forall t \in \mathcal{T},$$

where s_d is a *d*-dimensional summary function.

• Conditional Distance Independence Test (CDIT) (Wang et al., 2015) We still have many degrees of freedom.

Develop an ad-hoc test.

- Instead of testing $X_{it} \perp (b_{0i}, b_{1i}) | H_{i,t-1}, A_{i,t-1}, Y_{i,t}$ for all of t = 1, 2, ..., T,
- we test

$$X_{it} \perp (\hat{b}_{0i}, \hat{b}_{1i}) | s_d(H_{i,t-1}, A_{i,t-1}, Y_{i,t}) \quad \forall t \in \mathcal{T},$$

where s_d is a *d*-dimensional summary function.

Conditional Distance Independence Test (CDIT) (Wang et al., 2015)

We still have many degrees of freedom.

 Choice of d, the window width: Wider d brings curse of dimensionality narrower d brings false positives (undue dependence might appear).

Develop an ad-hoc test.

Instead of testing

 $X_{it} \perp (b_{0i}, b_{1i}) | H_{i,t-1}, A_{i,t-1}, Y_{i,t} \quad \text{for all of } t = 1, 2, ..., T,$

we test

$$X_{it} \perp (\hat{b}_{0i}, \hat{b}_{1i}) | s_d(H_{i,t-1}, A_{i,t-1}, Y_{i,t}) \quad \forall t \in \mathcal{T},$$

where s_d is a *d*-dimensional summary function.

Conditional Distance Independence Test (CDIT) (Wang et al., 2015)

We still have many degrees of freedom.

- Choice of d, the window width: Wider d brings curse of dimensionality narrower d brings false positives (undue dependence might appear).
- For what set of time points \mathcal{T} to test: single test: May not guarantee the results hold for all time points. testing on every other r time points.

Develop an ad-hoc test.

• Instead of testing

 $X_{it} \perp (b_{0i}, b_{1i}) | H_{i,t-1}, A_{i,t-1}, Y_{i,t} \quad \text{for all of } t = 1, 2, ..., T,$

we test

$$X_{it} \perp (\hat{b}_{0i}, \hat{b}_{1i}) | s_d(H_{i,t-1}, A_{i,t-1}, Y_{i,t}) \quad \forall t \in \mathcal{T},$$

where s_d is a d-dimensional summary function.

• Conditional Distance Independence Test (CDIT) (Wang et al., 2015)

We still have many degrees of freedom.

- Choice of *d*, the window width: Wider *d* brings curse of dimensionality narrower *d* brings false positives (undue dependence might appear).
- For what set of time points \mathcal{T} to test: single test: May not guarantee the results hold for all time points. testing on every other r time points.
- How to combine the tests: Bonferroni, Benjamini Hochberg, or L₂-norm summarization.

(UNC)

$$E(Y_{it+1}|H_{it},A_{it}=1)-E(Y_{it+1}|H_{it},A_{it}=0)$$
 , or $f_1(h_{it})^T\beta+g_1(h_{it})^TE(b_{1i}|H_{it}).$

$$E(Y_{it+1}|H_{it}, A_{it} = 1) - E(Y_{it+1}|H_{it}, A_{it} = 0)$$

, or $f_1(h_{it})^T \beta + g_1(h_{it})^T E(b_{1i}|H_{it}).$

• One possibility is to posit a linear model: $E(\hat{b}_{1ik}|H_{it}) = s_d(H_{it})^T \gamma_k, \qquad k = 1, 2, ..., K, t = 1, 2, ..., T.$

$$E(Y_{it+1}|H_{it}, A_{it} = 1) - E(Y_{it+1}|H_{it}, A_{it} = 0)$$

, or $f_1(h_{it})^T \beta + g_1(h_{it})^T E(b_{1i}|H_{it}).$

- One possibility is to posit a linear model: $E(\hat{b}_{1ik}|H_{it}) = s_d(H_{it})^T \gamma_k, \qquad k = 1, 2, ..., K, t = 1, 2, ..., T.$
- Then do the OLS.

$$E(Y_{it+1}|H_{it}, A_{it} = 1) - E(Y_{it+1}|H_{it}, A_{it} = 0)$$

, or $f_1(h_{it})^T \beta + g_1(h_{it})^T E(b_{1i}|H_{it}).$

- One possibility is to posit a linear model: $E(\hat{b}_{1ik}|H_{it}) = s_d(H_{it})^T \gamma_k, \qquad k = 1, 2, ..., K, t = 1, 2, ..., T.$
- Then do the OLS.
- We show $\hat{\gamma}_k$ is consistent.

• QKM's LMM can be naturally extended to non-linear one using kernels.

- QKM's LMM can be naturally extended to non-linear one using kernels.
- We use the Gaussian kernel width bandwidth $\gamma.$ By replacing the predictor with the kernel matrix and having an

- QKM's LMM can be naturally extended to non-linear one using kernels.
- We use the Gaussian kernel width bandwidth $\gamma.$ By replacing the predictor with the kernel matrix and having an
- L_2 -penalty term parametrized by λ , the model becomes a Bayesian LMM. Standard software can be used.

- QKM's LMM can be naturally extended to non-linear one using kernels.
- We use the Gaussian kernel width bandwidth $\gamma.$ By replacing the predictor with the kernel matrix and having an
- L_2 -penalty term parametrized by λ , the model becomes a Bayesian LMM. Standard software can be used.
- (γ, λ) can be tuned using cross-validation.

• You can use standard software to fit an LMM even with enogenous covariates.

- You can use standard software to fit an LMM even with enogenous covariates.
- But you have to make sure $X \perp b$ given history.

- You can use standard software to fit an LMM even with enogenous covariates.
- But you have to make sure $X \perp b$ given history.
- When the treatment effects on X contains some information on β , the partial likelihood might be inefficient

- You can use standard software to fit an LMM even with enogenous covariates.
- But you have to make sure $X \perp b$ given history.
- When the treatment effects on X contains some information on β , the partial likelihood might be inefficient
- Conditional independence test can be used as a diagnostic measures.

- You can use standard software to fit an LMM even with enogenous covariates.
- But you have to make sure $X \perp b$ given history.
- When the treatment effects on X contains some information on β , the partial likelihood might be inefficient
- Conditional independence test can be used as a diagnostic measures.
- When interested in marginal effects, it can be estimated by further positing a linear model.

- You can use standard software to fit an LMM even with enogenous covariates.
- But you have to make sure $X \perp b$ given history.
- When the treatment effects on X contains some information on β , the partial likelihood might be inefficient
- Conditional independence test can be used as a diagnostic measures.
- When interested in marginal effects, it can be estimated by further positing a linear model.
- LMM can be extended using a kernel extension.

References I

(UNC)